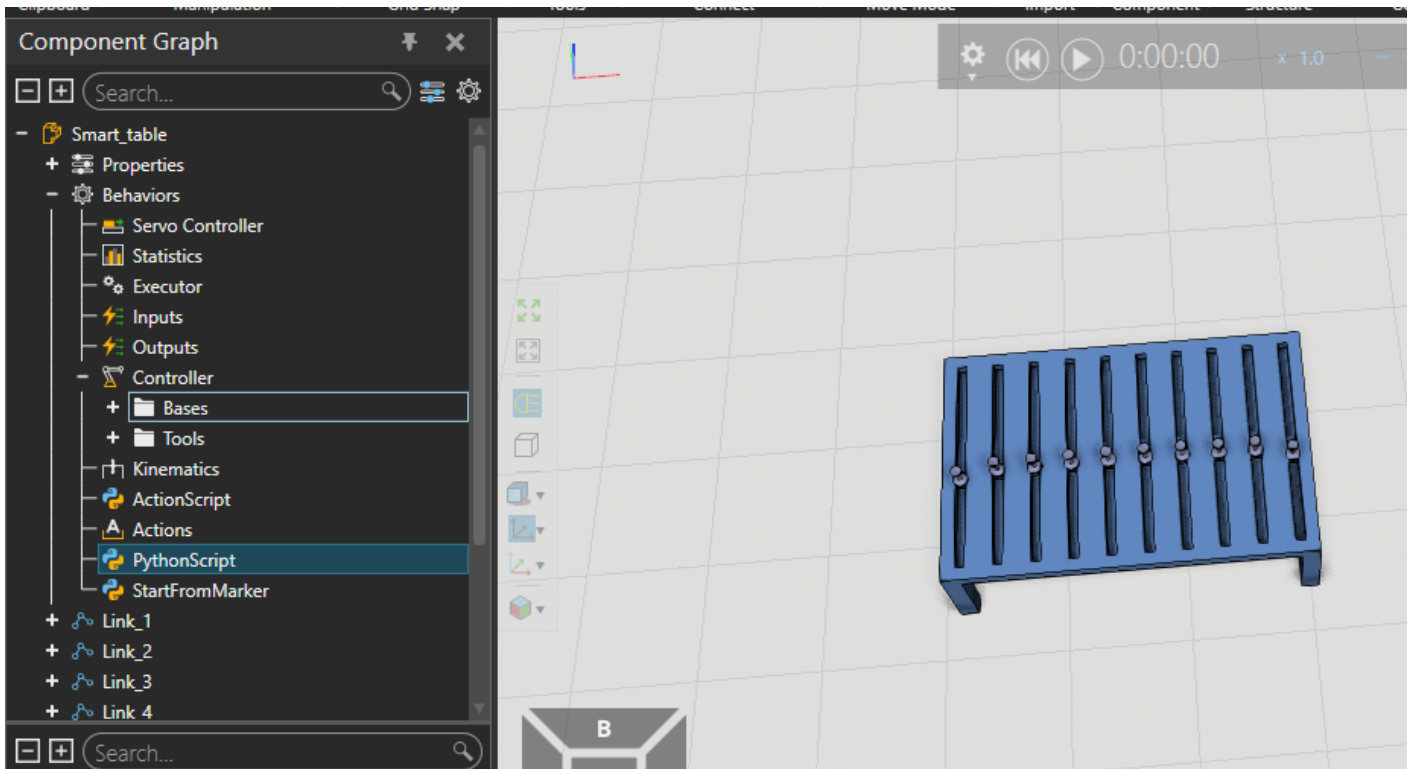


Управление кастомными servo



```
from vcScript import *

comp = GetComponent()
servo = comp.findBehaviour("Servo Controller")

def OnSignal( signal ):
    pass

def OnRun():
    servo.setJointTarget(0, -342.0)
    servo.setJointTarget(1, -10.0)
    servo.setJointTarget(2, 400.0)
    servo.setJointTarget(3, -512.0)
    servo.setJointTarget(4, -172.0)
    servo.setJointTarget(5, 122)
```

```
servo.setMotionTime(1.0)
print servo.calcMotionTime()
servo.move()
```

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